



VK16D32AQ Datasheet

8×12 Constant Current LED Driver

Rev.1.1

Intellectual Property Statement:

Shenzhen Vinka Microelectronics Co., Ltd. (hereinafter referred to as “the Company”) owns legally registered intellectual property rights in both domestic and international jurisdictions. Any unauthorized use of the Company’s products or patented technologies by individuals or organizations is strictly prohibited.

The Company reserves the right to take legal action against any infringement, and to seek full compensation for damages or unlawful gains.

The Company’s name and trademarks are legally protected and may not be used or imitated without explicit written permission. No implied or express license shall be granted under any circumstances.

1 General Description

VK16D32AQ is a dedicated chip for constant current digital tube or dot matrix LED driver control, integrating circuits such as a data latch and an LED constant current driver module internally. The bit number of scanning can be adjusted through register configuration to obtain a larger single-point driving current. The data communicates with the MCU through the I2C communication interface. The SEG pin is connected to the anode of the LED, and the GRID pin is connected to the cathode of the LED, which can support dot matrix LED display panels ranging from 8SEG×1GRID to 8SEG×12GRID. It adopts the SSOP24 packaging form and is suitable for driving small LED display screens.

Compared with the traditional LED display panel driver chips, when the number of lit LED changes or the input voltage varies, the current of a single LED will change, thereby affecting the display brightness. It adopts a constant current design. Once the display mode is configured, the current of each LED remains constant and will not fluctuate due to changes in the number of lit LED or input voltage.

2 Key Features

- Operating voltage:3.0-5.5V
- Integrated RC oscillator
- 8 SEG and 12 GRID (can be selected from 1 to12)
- SEG pins connect to LED Anode , GRID pins connect to LED Cathode
- I2C communication interface
- 16 levels of overall brightness adjustable (SEG constant current setting 16 levels)
- The built-in display RAM is 8×12 bits
- Built-in power-on reset circuit
- Output constant current
- It has a large driving current and is suitable for high-brightness display applications
- Available Packages:
QFN24L(4.0mm × 4.0mm × 0.75mm-0.50mm)

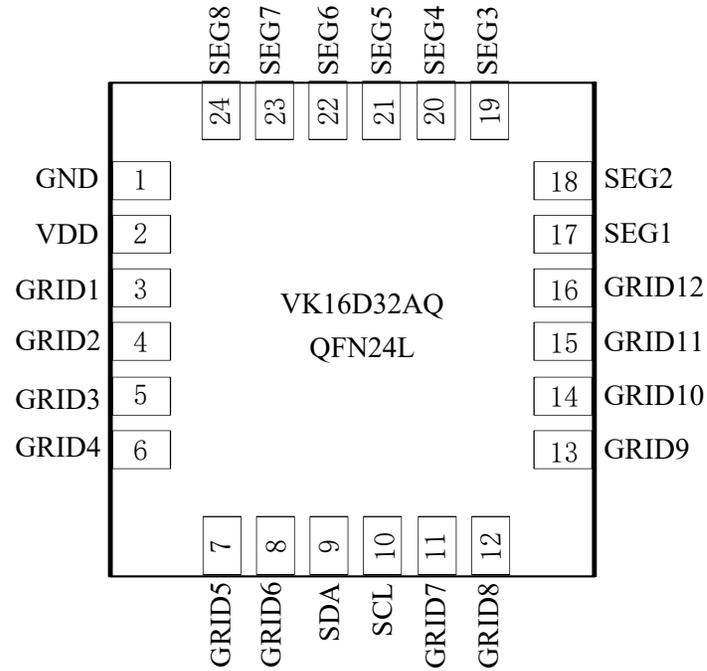
3 Product Selection

Part No.	VK16D32	VK16D32AQ	VK16D33	VK16D33AA	VK16D33AQ	VK16D33Q
Max. LED	96	96	128	128	128	128
SEG/GRID	8/12	8/12	8/16	8/16	8/16	8/16
Packaging	SSOP24	QFN24L	SOP28	SSOP28	QFN28L	QFN32L

4 Ordering Information

Part No.	Packaging	Tube Qty	Tray Qty	Box Qty	Total Qty	Notes
VK16D32	SSOP24	50/tube		10000/box	100000PCS	
VK16D32AQ	QFN24L		490/tray	4900/box	29400PCS	
VK16D33	SOP28	26/tube		2080/box	20800PCS	
VK16D33AA	SSOP28		4000/tray	8000/box	64000PCS	
VK16D33AQ	QFN28L		490/tray	4900/box	29400PCS	
VK16D33Q	QFN32L		490/tray	4900/box	29400PCS	

5 Package Pinout Information(QFN24L)



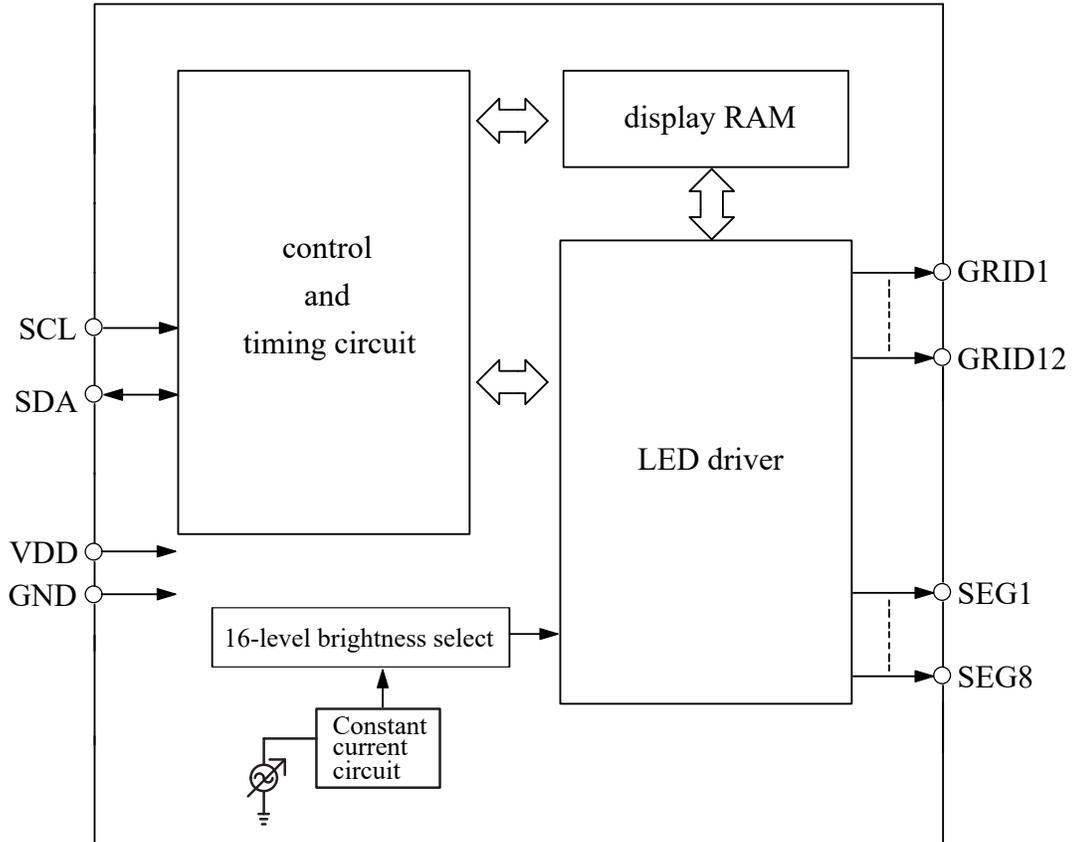
For more information: [Page 14](#)

5.1 VK16D32AQ/QFN24L Pin Description

No.	Name	I/O	Function
17~24	SEG1~SEG8	O	LED SEG drive outputs
1	GND	GND	Negative power supply
2	VDD	VDD	Positive power supply
3~8 11~16	GRID1 ~GRID6 GRID7~GRID12	O	LED GRID drive outputs
9	SDA	I/O	The I2C serial data input/output pins need to be connected to an external pull-up resistor
10	SCL	I	The I2C serial clock pin requires an external pull-up resistor

6 Functional Description

6.1 Block Diagram



6.2 Display RAM

The static display memory (RAM) has a structure of 8×12 bits and stores the displayed data. The content of RAM is directly mapped to the display content of the LED driver, with the display address ranging from 0x00 to 0x0C, and there are a total of 12 display units. If you want to turn on or off a certain LED, simply set the corresponding display RAM bit to 1 or 0. For example, to control the on/off of LED1 driven by pins SEG1 and GRID1, simply set the bit0 of the corresponding display RAM (address 0x00) to 1 or 0.

The process of mapping the contents in RAM to LED is shown in the following table:

SEG GRID	SEG8	SEG7	SEG6	SEG5	SEG4	SEG3	SEG2	SEG1	Address
GRID1									0x00
GRID2									0x01
GRID3									0x02
GRID4									0x03
GRID5									0x04
GRID6									0x05
⋮									⋮
GRID10									0x0A
GRID11									0x0B
GRID12									0x0C
	D7	D6	D5	D4	D3	D2	D1	D0	

Note:

1. During Power on, the displayed RAM value may be random. It is recommended that customers clear the display RAM to 0 after power on, that is, after power on, write 0x00 to all display RAM (address 0x00-0x0C)
2. The SEG pins must be connected to the LED Anode, and the GRID pins must be connected to the LED Cathode and cannot be reversed.

7 I2C communication command

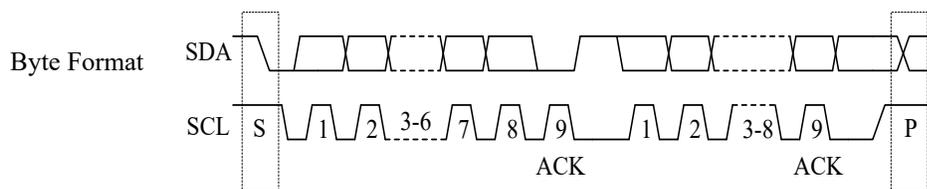
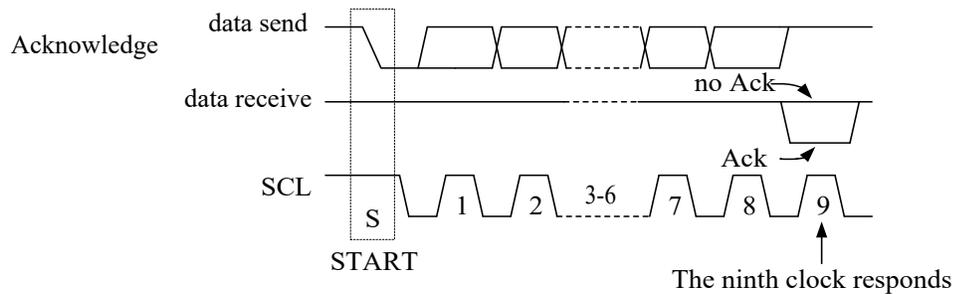
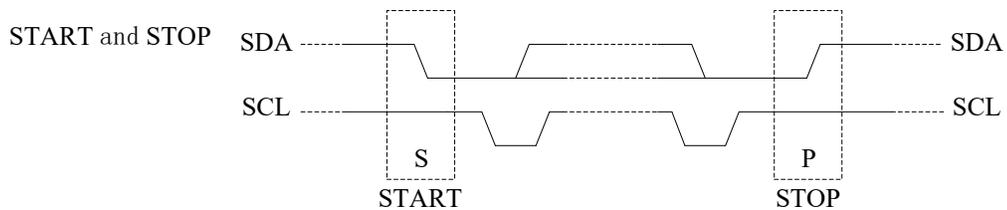
7.1 I2C communication interface

The VK16D32AQ has two communication pins and follows the I2C protocol, with a maximum communication speed of 400kbit/S.

The SCL pin is the clock input pin, and the SDA pin is the serial data input/output pin, which requires an external pull-up resistor.

When the I2C bus is idle, both pins are at a high level. When the SCL signal is at a high level and the SDA signal changes from a high level to a low level, the operation starts or resumes. Conversely, when the SCL signal is at a high level and the SDA signal changes from a low level to a high level, the operation stops.

When the SCL signal is at a high level, the data on the SDA port is all valid and stable. Only when the SCL signal is at a low level can the level on the SDA port be changed.



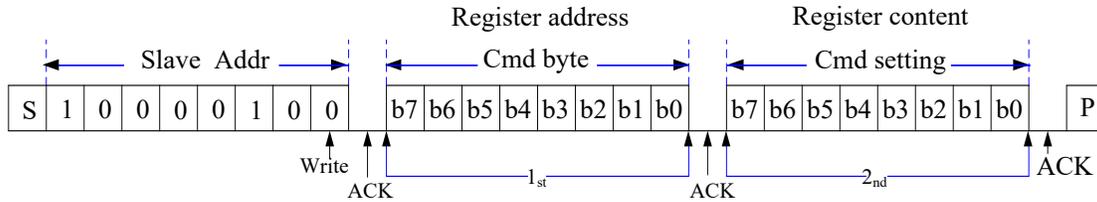
Slave Address
(0x84) bit0-R/W

1	0	0	0	0	1	0	0
---	---	---	---	---	---	---	---

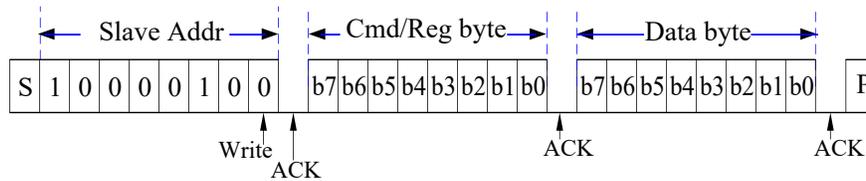
7.2 I2C Command Format

Write Operation

Write Command



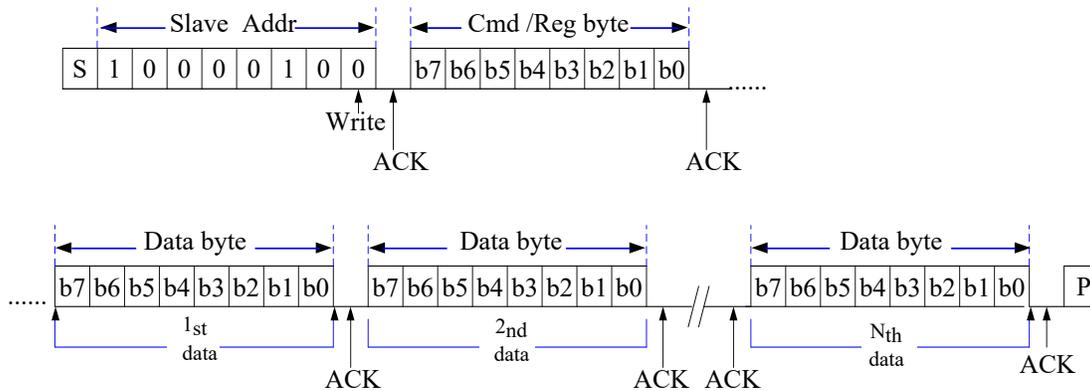
Write a single byte of data to display RAM



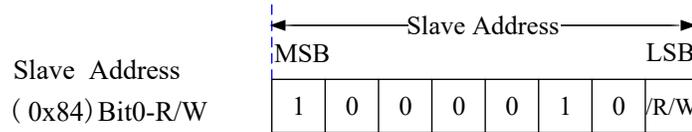
Note:

If the byte after the Slave address is a command code, the byte after the command code is ignored.

Write multiple bytes of data to the display RAM



7.3 Command Description



After power on, the status control command (register 0x12) needs to be configured to 0x01 (work state).

Command(Register) writing sequence:

State control command → Display data command → Display control command → status control command.

Note: Once bit0 of the State control register is configured as "0", when rewriting data, be sure to configure the State control register to 0x01 before performing other operations.

8 Display control command

Select display brightness (16 levels)

Register Address	Register content								Function			
	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	Display brightness level (SEG continuous current)			
0x10	----- 0				1	1	1	1	70mA(default)			
					1	1	1	0	65.6mA			
					1	1	0	1	61.3mA			
					-----				-----			
					0	0	0	1	8.75mA			
					0	0	0	0	4.37mA			

Select number of scan GRID ,default 12GRID.

Register Address	Register content								Function			
	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	number of scan GRID			
0x11	----- 0				1	0	1	1	12GRID(default)			
					1	0	1	0	11GRID			
					1	0	0	1	10GRID			
					-----				-----			
					0	0	0	0	1GRID			

8.1 Status control command

Register Address	Register content								Function	
	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	work state	
0x12	----- 0								0	Shutdown(default)
									1	Normal operation
								0		display off(default)
								1		display on

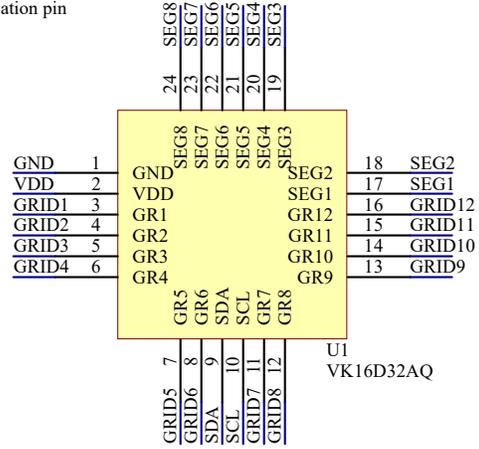
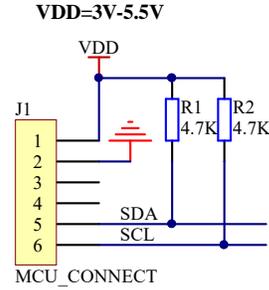
8.2 Display data command

The display data address ranges from 0x00 to 0x0C, totaling 12 bytes, corresponding respectively to the LED lights of the matrices connected to the SEG and GRID pins.

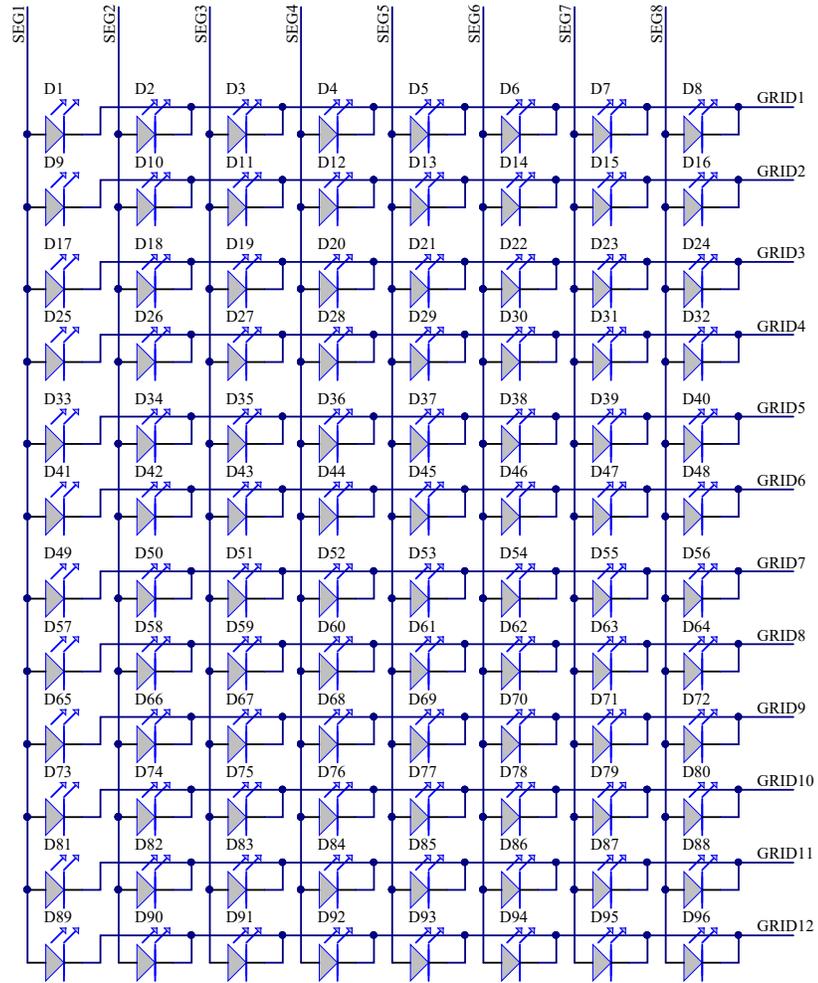
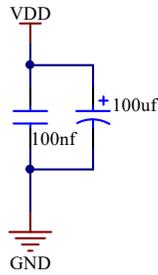
display data address	display content								Function
	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0	display data
0x00-0x0C	X	X	X	X	X	X	X	X	1 bit control 1 LED (by 1SEG and 1 GRID)

9 Application Circuits

When the surrounding interference is relatively large, a 10R to 10k resistor and a PF-level small capacitor to ground can be connected in series on the communication pin. When the power supply of the single-chip microcomputer (3.3V) and the driver chip (5V) is inconsistent, it is recommended to add a level conversion circuit on the communication pin



The filter capacitor between VDD and GND should be placed as close to the chip as possible on the PCB board for strong filtering effect.



Connect the SEG pin to the anode of the LED and the GRID pin to the cathode of the LED

10 Electrical Characteristics

10.1 Absolute Maximum Ratings

Parameter	Symbol	Ratings	Unit
Supply voltage	VDD	-0.3~6.0	V
Input Voltage	VIN	VSS-0.5~VDD+0.5	V
Drive output current	IOLGRID Σ ¹ 16	+600	mA
	IOHSEG	-72	mA
Power loss	PD	500	mW
Thermal resistance	θ_{JA}	128	°C/W
Storage Temperature	TSTG	-65~+150	°C
Operating Temperature	TOTG	-40~+85	°C

10.2 DC Electrical Characteristics

Parameter	Symbol	Test Condition	Min.	Typ.	Max.	Unit
High Level output Current	IOHSG	Vo=VDD-1V SEG1~SEG8	-63	-70	-77	mA
Low Level output Current	IOLGOUT	Vo=0.8V	—	560	—	mA
Input Current	IIN	VI=VDD, SDA, SCL	—	—	±1	uA
High-level Input	VIH	SDA,SCL	0.7VDD	—	5	V
Low-level Input	VIL	SDA,SCL	0	—	0.3VDD	V
Hysteresis voltage	VH	SDA,SCL	—	0.35	—	V
Dynamic current loss	IDD_DYN	Noload/LED OFF	—	—	1	mA
shutdown Current	ISHUT	Shutdown enable			10	uA

10.3 AC Electrical Characteristics

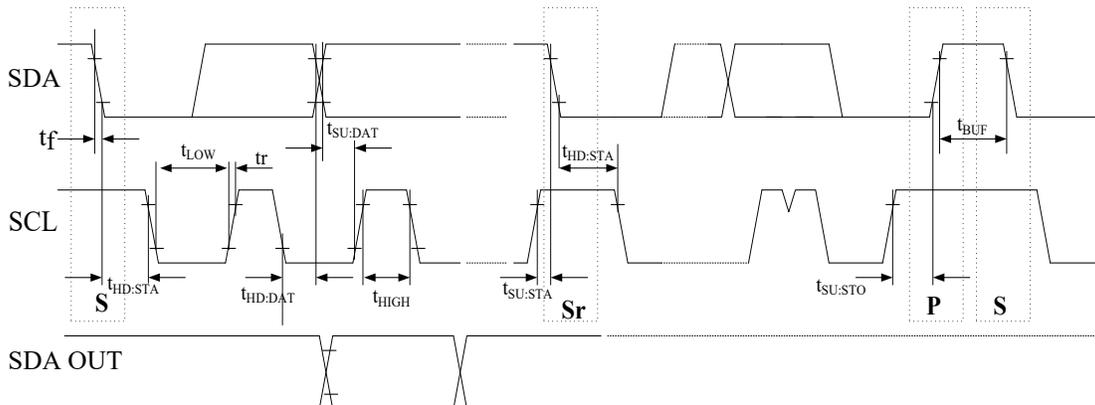
Switch Parameters

Parameter	Symbol	Test Condition	Min.	Typ.	Max.	Unit
Rising Time	TTZH1	SEG1~8,CL=300pF	—	—	2	us
	TTZH2	GRID1~12,CL=300pF	—	—	0.5	us
Falling Time	TTZH	CL=300pF, SEGn, GRIDn	—	—	120	us

Timing Parameters

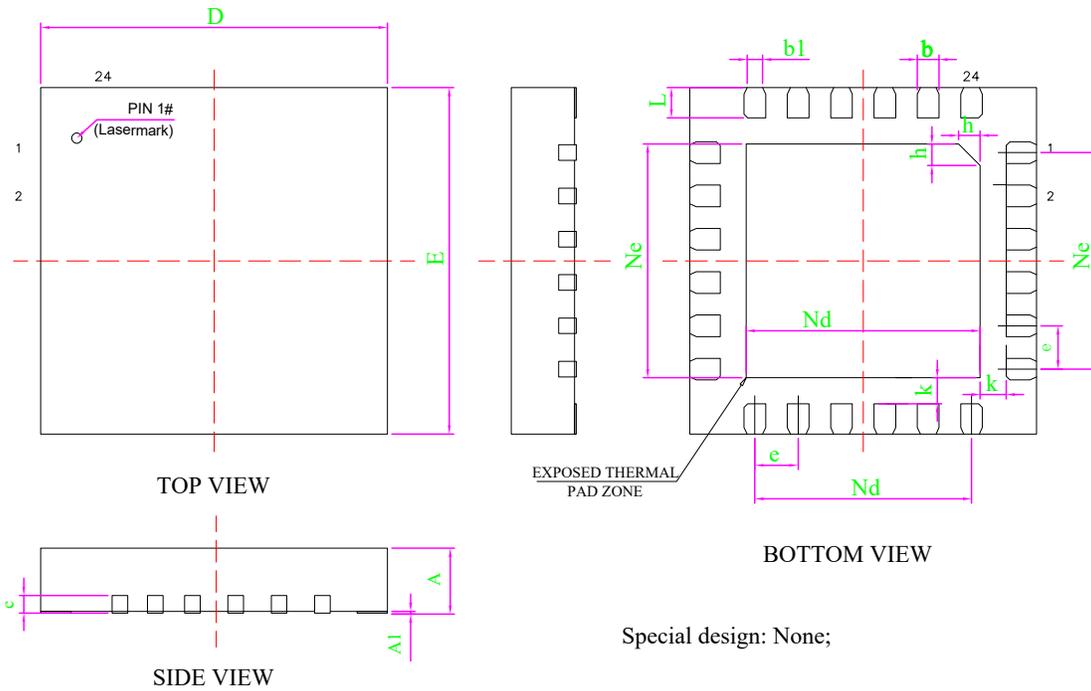
Parameter	Symbol	Min.	Typ.	Max.	Unit	Test Condition
SCL clock frequency	F _{SCL}	-	-	400	KHz	
Bus Free Time	t _{BUF}	1.3	-	-	μS	Time in which the bus must be free before a new transmission can start
Start Condition Hold Time	t _{HD:STA}	0.6	-	-	μS	After this cycle, the first clock pulse is generated
SCL Low Time	t _{LOW}	1.3	-	-	μS	
SCL High Time	t _{HIGH}	0.6	-	-	μS	
Start Condition Setup Time	t _{SU:STA}	0.6	-	-	μS	Only relevant for repeated START condition
Data Hold Time	t _{HD:DAT}	-	-	0.9	nS	
Data Setup Time	t _{SD:DAT}	100	-	-	nS	
SDA , SCL Rising Time	t _r	20+0.1Cb1	-	-	nS	periodically sampled
SDA,SCL Falling Time	t _f	20+0.1Cb	-	-	nS	periodically sampled
Stop Condition Setup Time	t _{SU:STO}	-	-	-	μS	

I²C Timing



11 Package Information

11.1 QFN24L(4.0mm × 4.0mm × 0.75mm-0.50mm)



Dimensions			
SYMBOL	MIN	NOMINAL	MAX
A	0.70	0.75	0.80
A1	0	0.02	0.05
b	0.20	0.25	0.30
b1	0.18REF		
c	0.203REF		
D	3.90	4.00	4.10
D2	2.60	2.70	2.80
e	0.50BSC		
Ne	2.50BSC		
Nd	2.50BSC		
E	3.90	4.00	4.10
E2	2.60	2.70	2.80
L	0.30	0.35	0.40
h	0.20	0.25	0.30
K	0.30REF		

12 Disclaimer

Warranty and liability — The information provided in this document is believed to be accurate and reliable. However, Shenzhen Vinka Microelectronics Co., Ltd. (hereinafter “the Company”) makes no warranties, express or implied, as to the completeness or suitability of this information for any specific purpose.

In no event shall the Company be liable for any indirect, incidental, or consequential damages, including but not limited to loss of profits, equipment damage, or system failure, arising out of the use of this product or documentation, regardless of the legal theory under which such liability is asserted.

Right to change — The Company reserves the right to modify any information contained herein without prior notice. The latest version of this document is available at:

<https://www.szvinka.com/>

Applicability — This product is not designed or intended for use in life-critical, medical, or safety systems where failure could result in injury or death. The customer shall assume full responsibility for any such use.

Application — All product application descriptions provided herein are intended for illustrative purposes only.

The Company makes no representations or warranties, express or implied, regarding the suitability of any specific application without further testing or modification.

The customer is solely responsible for determining whether the Company’s products are appropriate for their intended applications or end customers.

The customer shall ensure proper design practices, implementation safeguards, and operational validation to minimize risks associated with product use.

The Company shall not be held liable for any defects, losses, costs, or damages arising from weaknesses or failures in the customer’s own products or applications, or from the integration or use of third-party products.

Furthermore, the customer shall conduct all necessary testing and validation for any third-party deployment of the Company’s products to avoid potential misuse or associated damages. The Company assumes no liability in this regard.

Commercial terms of sale — Unless otherwise agreed in writing, sales of this product are subject to the Company’s standard terms and conditions of sale. The Company expressly rejects the applicability of the customer’s general terms and conditions.

Export control — This product may be subject to applicable export control regulations. The customer is solely responsible for compliance with such regulations, including obtaining any necessary export licenses.

13 Revision History

No.	Version	Date	Modify the content	Check
1	1.0	2022-08-09	Initial release	YES
2	1.1	2025-10-21	Change Description	YES

[1] Please refer to the latest version of this document before starting or finalizing any design.

[2] Since the release of this document, the status or availability of this product may have changed. For the most up-to-date information, please visit:

<https://www.szvinka.com/>